Generalized Harmonic Evolutions of Binary Black Hole Spacetimes

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Collaborators: Larry Kidder, Robert Owen, Oliver Rinne, Harald Pfeiffer, Mark Scheel, Saul Teukolsky

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Moving Black Holes.

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- Dual Coordinate Frame Evolution Method.
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- Binary Black Hole Evolutions.

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Solution:

Choose coordinates that smoothly track the location of the black hole.



Evolving Black Holes in Rotating Frames

- Coordinates that rotate with respect to the inertial frames at infinity are needed to track the horizons of orbiting black holes.
- Evolutions of Schwarzschild in rotating coordinates are unstable.



- Evolutions shown use a computational domain that extends to r = 1000M.
- Angular velocity needed to track the horizons of an equal mass binary at merger is about Ω ≈ 0.2/M.
- Problem caused by asymptotic behavior of metric in rotating coordinates: ψ_{tt} ~ ρ²Ω², ψ_{ti} ~ ρΩ, ψ_{ij} ~ 1.

Dual-Coordinate-Frame Evolution Method

 Single-coordinate frame method uses the one set of coordinates, x^ā = {t̄, xⁱ}, to define field components, u^ā = {ψ_{āb}, Π_{āb}, Φ_{īāb}}, and the same coordinates to determine these components by solving Einstein's equation for u^ā = u^ā(x^ā):

$$\partial_{\bar{t}} u^{\bar{\alpha}} + A^{\bar{k}\bar{\alpha}}{}_{\bar{\beta}} \partial_{\bar{k}} u^{\bar{\beta}} = F^{\bar{\alpha}}.$$

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$$\partial_{\bar{t}} u^{\bar{\alpha}} + A^{\bar{k}\bar{\alpha}}{}_{\bar{\beta}} \partial_{\bar{k}} u^{\bar{\beta}} = F^{\bar{\alpha}}.$$

 Dual-coordinate frame method uses a second set of coordinates, x^a = {t, xⁱ} = x^a(x^ā), to determine the original representation of the dynamical fields, u^ā = u^ā(x^a), by solving the transformed Einstein equation:

$$\partial_t u^{\bar{\alpha}} + \left[\frac{\partial x^i}{\partial \bar{t}} \delta^{\bar{\alpha}}{}_{\bar{\beta}} + \frac{\partial x^i}{\partial x^{\bar{k}}} A^{\bar{k}\bar{\alpha}}{}_{\bar{\beta}} \right] \partial_i u^{\bar{\beta}} = F^{\bar{\alpha}}.$$

Testing Dual-Coordinate-Frame Evolutions

• Single-frame evolutions of Schwarzschild in rotating coordinates are unstable, while dual-frame evolutions are stable:



Single Frame Evolution



• Dual-frame evolution shown here uses a comoving frame with $\Omega = 0.2/M$ on a domain with outer radius r = 1000M.

Horizon Tracking Coordinates

- Coordinates must be used that track the motions of the holes.
- For equal mass non-spinning binaries, the centers of the holes move only in the z = 0 orbital plane.

$$\begin{pmatrix} x \\ y \\ z \end{pmatrix} = e^{a(\bar{t})} \begin{pmatrix} \cos \varphi(\bar{t}) & -\sin \varphi(\bar{t}) & 0 \\ \sin \varphi(\bar{t}) & \cos \varphi(\bar{t}) & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} \bar{x} \\ \bar{y} \\ \bar{z} \end{pmatrix},$$

with $t = \overline{t}$, is general enough to keep the holes fixed in co-moving coordinates for suitably chosen functions $a(\overline{t})$ and $\varphi(\overline{t})$.

Since the motions of the holes are not known *a priori*, the functions *a*(*t*) and φ(*t*) must be chosen dynamically and adaptively as the system evolves.

Horizon Tracking Coordinates II



- Measure the comoving centers of the holes: $x_c(t)$ and $y_c(t)$, or equivalently $Q^x(t) = [x_c(t) x_c(0)]/x_c(0)$ and $Q^y(t) = y_c(t)/x_c(t)$.
- Choose the map parameters a(t) and φ(t) to keep Q^x(t) and Q^y(t) small.

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- Choose the map parameters a(t) and φ(t) to keep Q^x(t) and Q^y(t) small.
- Changing the map parameters by the small amounts, δa and δφ, results in associated small changes in δQ^x and δQ^y:

$$\delta \mathbf{Q}^{\mathbf{x}} = -\delta \mathbf{a}, \qquad \quad \delta \mathbf{Q}^{\mathbf{y}} = -\delta \varphi.$$

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• Measure the quantities $Q^{y}(t)$, $dQ^{y}(t)/dt$, $d^{2}Q^{y}(t)/dt^{2}$, and set

$$\frac{d^{3}\varphi}{dt^{3}} = \lambda^{3}Q^{y} + 3\lambda^{2}\frac{dQ^{y}}{dt} + 3\lambda\frac{d^{2}Q^{y}}{dt^{2}} = -\frac{d^{3}Q^{y}}{dt^{3}}.$$

The solutions to this "closed-loop" equation for Q^{y} have the form $Q^{y}(t) = (At^{2} + Bt + C)e^{-\lambda t}$, so Q^{y} always decreases.

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- In the time interval $t_i < t < t_{i+1}$ we set:

$$\begin{split} \varphi(t) &= \varphi_i + (t-t_i) \frac{d\varphi_i}{dt} + \frac{(t-t_i)^2}{2} \frac{d^2\varphi_i}{dt^2} \\ &+ \frac{(t-t_i)^3}{2} \left(\lambda \frac{d^2 Q_i^y}{dt^2} + \lambda^2 \frac{dQ_i^y}{dt} + \lambda^3 \frac{Q_i^y}{3} \right), \end{split}$$

where Q^x , Q^y , and their derivatives are measured at $t = t_i$, so these maps satisfy the closed loop equation at $t = t_i$.

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where Q^x , Q^y , and their derivatives are measured at $t = t_i$, so these maps satisfy the closed loop equation at $t = t_i$.

• This works! We are now able to evolve binary black holes using horizon tracking coordinates until just before merger.



Evolving Binary Black Hole Spacetimes

• We can now evolve binary black hole spacetimes with excellent accuracy and computational efficiency through many orbits.



Improved Circular Orbit Initial Data

- The conformal thin sandwich initial data has initial radial velocity $\dot{R} = 0$. True circular orbit initial data should have $\dot{R} < 0$, but small.
- Conformal thin sandwich initial data therefore results in slightly elliptical orbits:



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- Small changes in the initial R and Ω gives a more circular orbit.
- Orbit point with R = 0 is near apcenter, with larger R than corresponding point in circular orbit.
- Orbits at time shifted points have nearly identical gravitational waveforms.